

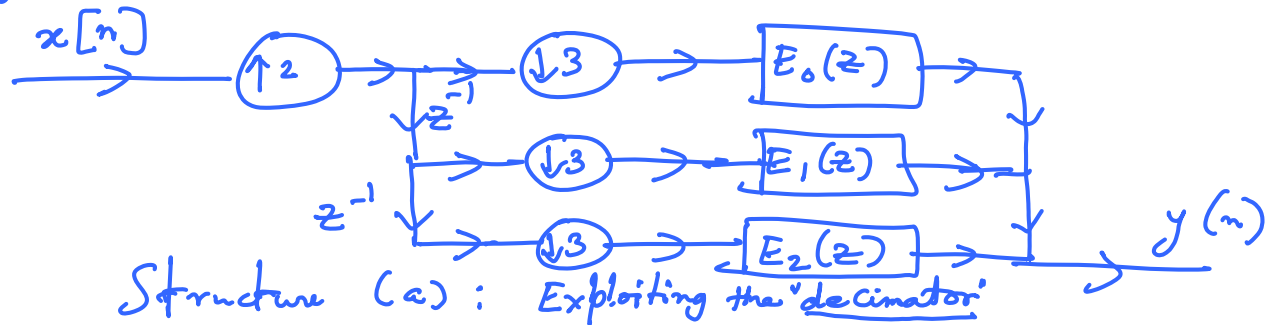
## Efficient structures for fractional decimation

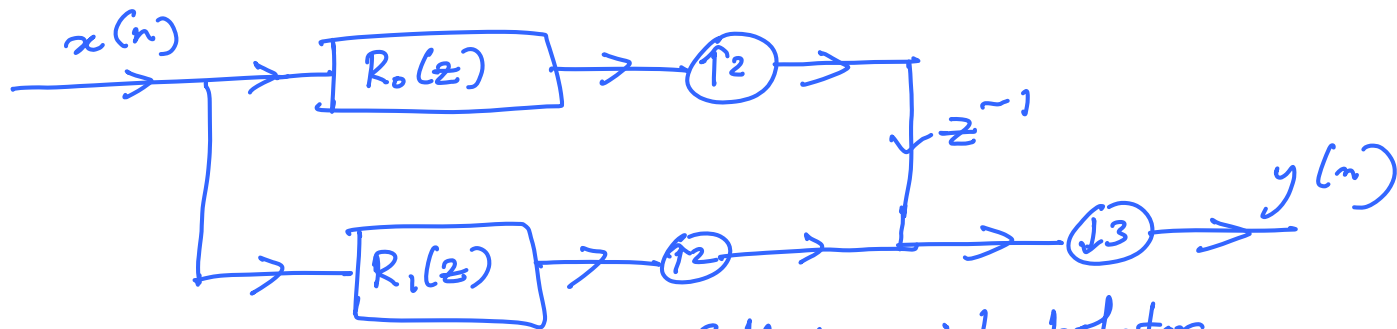
For doing a  $M/L$  decimation, w/o polyphase we are 'inefficient'

- 1) At any point in time,  $L-1$  out of  $L$  multipliers have zero inputs.
- 2) Only one out of  $M$  o/p samples is being retained.

Consider  $M=3$  and  $L=2$

Using type 1 polyphase decomposition,





Structure (b): Exploiting interpolator

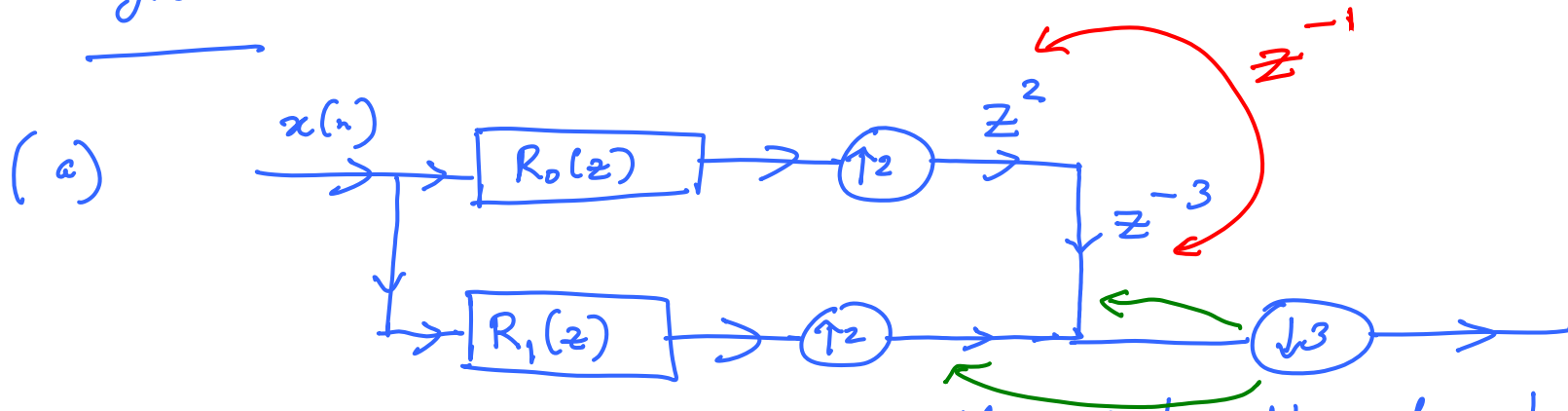
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Q<sub>n</sub>:

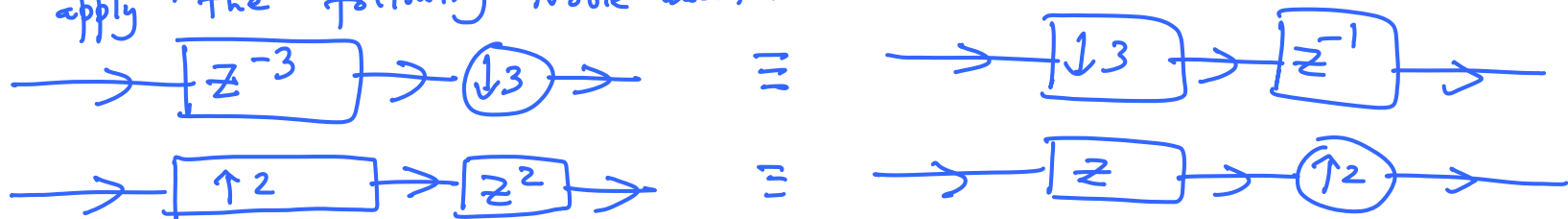
Can we exploit both (a) and (b) to take  
"full advantage" of decimator & expander?

We adopt a technique by Hsiao (1990) (Efficient architecture)

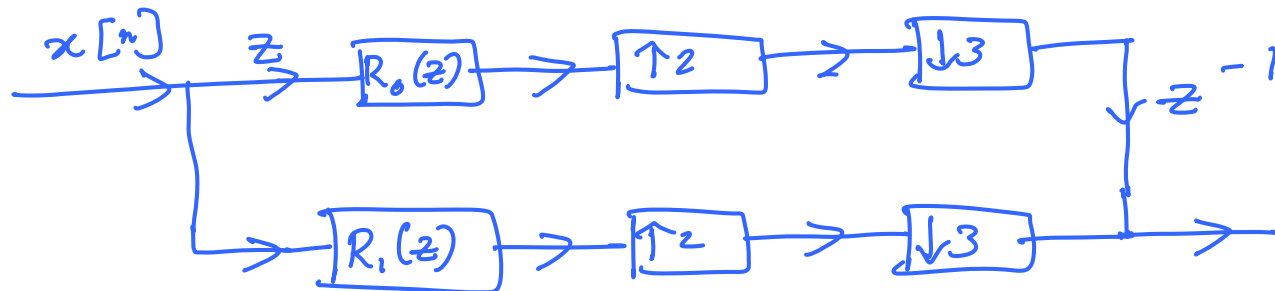
Trick:  $z^{-1} = z^{-3} \cdot z^2$



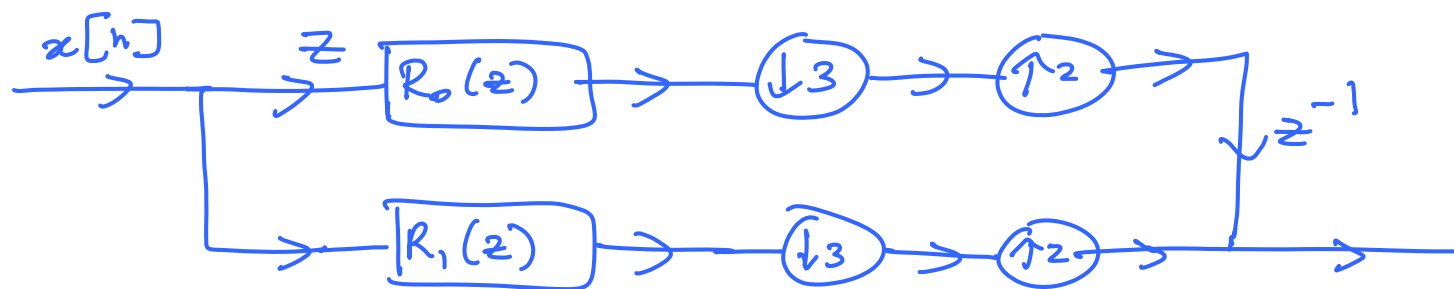
Next, we push the down sampler into the branches before, and apply the following Noble identities.



(b)



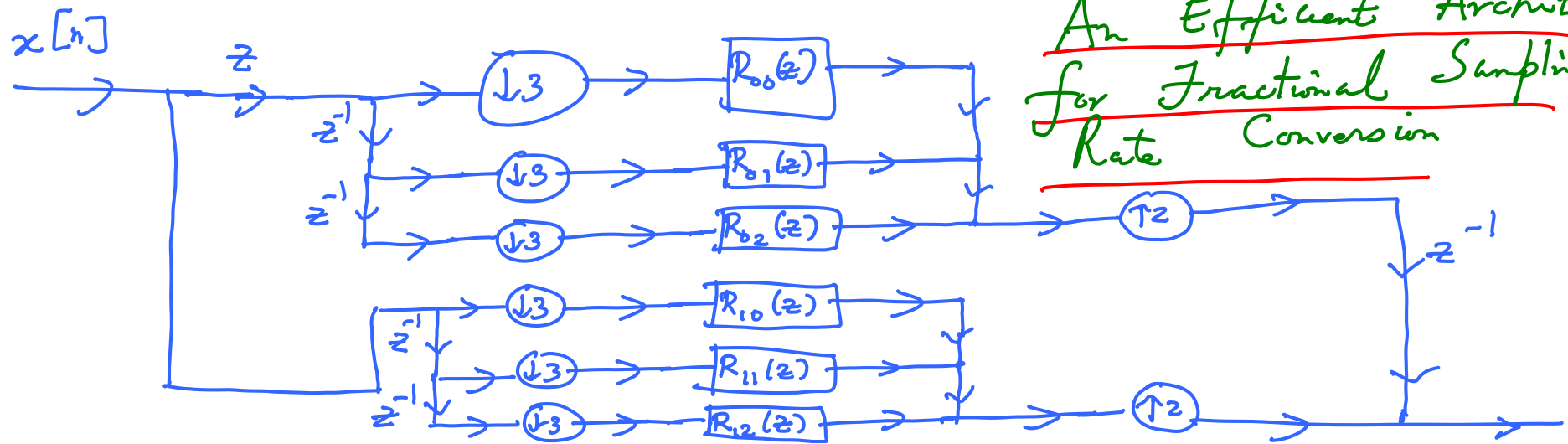
Let us interchange the decimator & the expander  
since  $\text{gcd}(3, 2) = 1$



(c) Let us do a type 1 polyphase decomposition on  
 Components  $R_0(z)$  &  $R_1(z)$

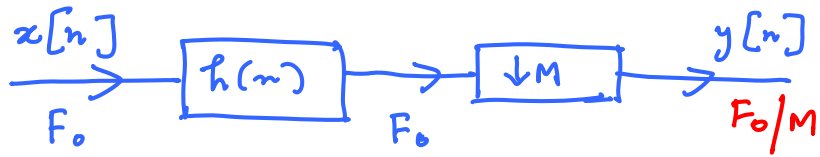
$$R_0(z) = R_{00}(z^3) + z^{-1} R_{01}(z^3) + z^{-2} R_{02}(z^3)$$

$$R_1(z) = R_{10}(z^3) + z^{-1} R_{11}(z^3) + z^{-2} R_{12}(z^3)$$

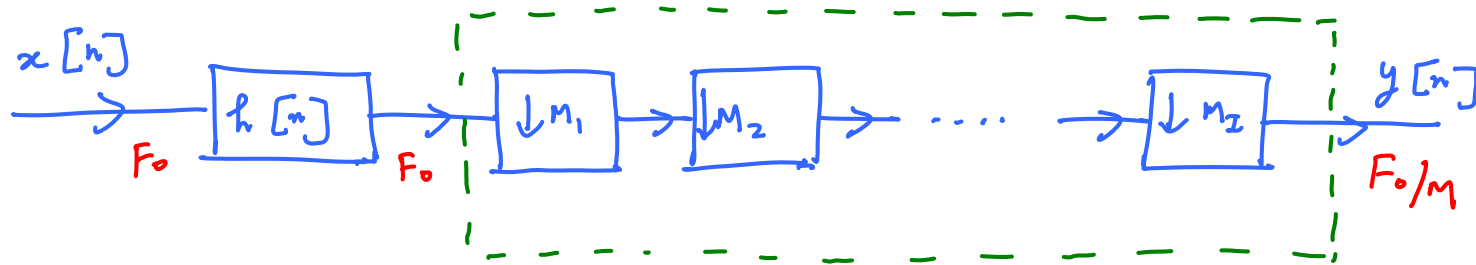


An Efficient Architecture  
for Fractional Sampling  
Rate Conversion

# MultiStage Implementations

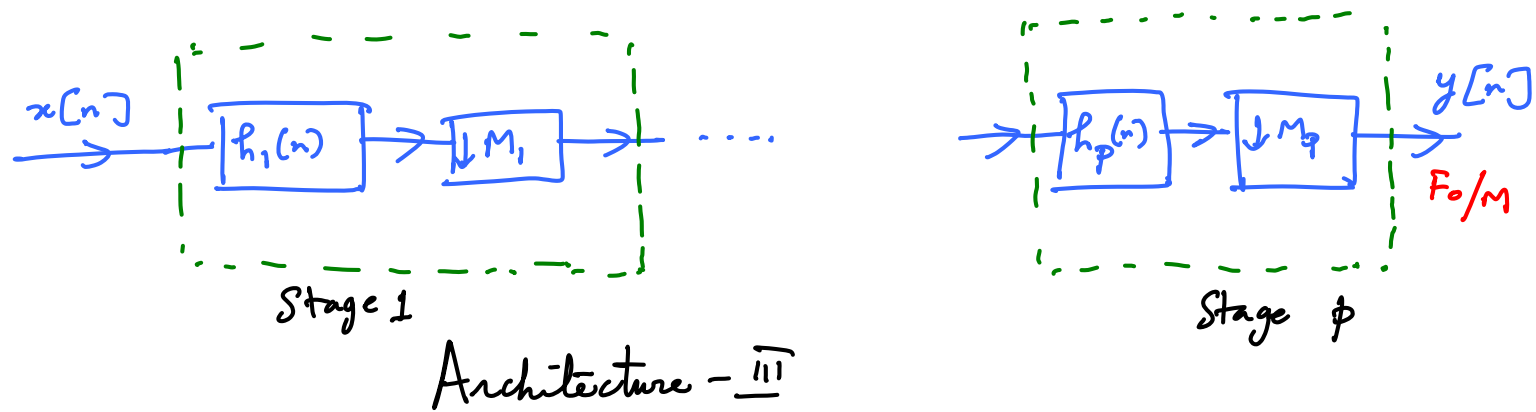


## Architecture - I



## Architecture - II

$$M = \prod_{i=1}^I M_i$$

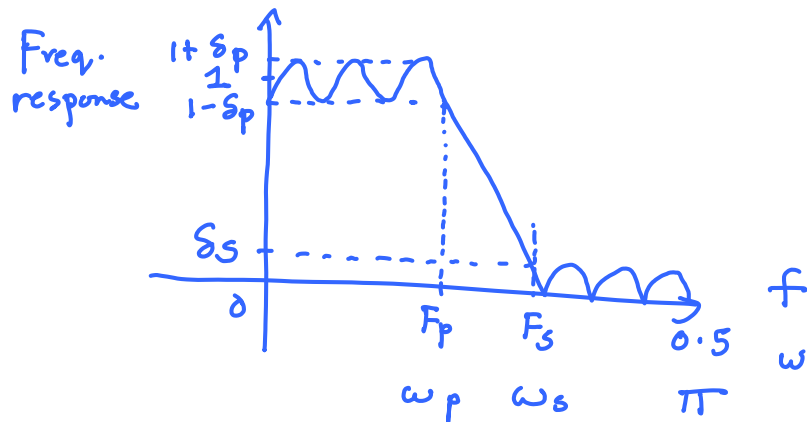


Question : It seems obvious that we are greatly increasing the computations by having many intermediate filters at various stages. This is opposite to our intention.

Goal : To show why multistage structures are advantageous over a single stage.

## Design Example

A signal  $x(n)$  with sampling rate  $10\text{KHz}$  is to be down sampled by a factor  $M = 100$  to produce a signal at  $100\text{ Hz}$  rate. The pass band of the signal is from  $0 - 45\text{ Hz}$  and the band from  $45 - 50\text{ Hz}$  is the transition band. A pass band ripple of  $0.01$  and a stop band ripple of  $0.001$  are desired/required.



$$F_s = 50\text{ Hz}$$

$$F_p = 45\text{ Hz}$$

$$\Delta F = 5\text{ Hz}$$

$$\delta_p = 0.01$$

$$\delta_s = 0.001$$



$$N = 1 + \frac{D_{\infty}(\delta_p, \delta_s)}{\Delta F/F} - f(\delta_p, \delta_s) \Delta F/F$$

$$D_{\infty}(\delta_p, \delta_s) = \left[ a_1 (\log_{10} \delta_p)^2 + a_2 \log(\delta_p) + a_3 \right] \log(\delta_s) + \left[ a_4 (\log_{10} \delta_p)^2 + a_5 \log_{10}(\delta_p) + a_6 \right]$$

$$a_1 = 5.3e-3$$

$$a_3 = -0.4761$$

$$a_5 = -0.5941$$

$$a_2 = 0.071$$

$$a_4 = -0.0026$$

$$a_6 = -0.4278$$

Ref: L. R. Rabiner et al.

Some comparisons of FIR and IIR digital filters

Bell. Sys. Tech. Journal, vol. 53, no. 2, Feb. 1974.

$$f(\delta_p, \delta_s) = 0.512 \log_{10} \left( \frac{\delta_p}{\delta_s} \right) + 11.01$$

Less accurate but simplified version

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$$N = \frac{-10 \log_{10} (\delta_p \cdot \delta_s) - 15}{14 \Delta F / F} + 1$$

Let us compute all the quantities

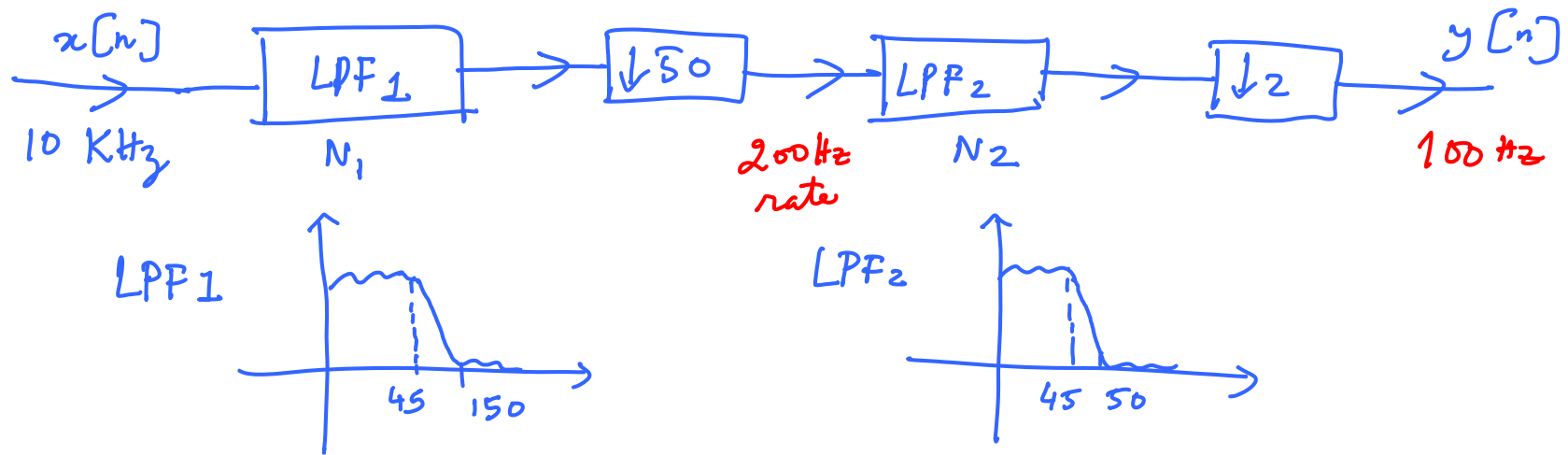
(For Single Stage)  
design

$$N \approx \frac{D_{\infty}(\delta_p, \delta_s)}{\Delta F/F} \approx \frac{D_{\infty}(0.01, 0.001)}{5/10 \text{ kHz}} = 5080$$

The # of multiplications / sec. needed to implement this

would be  $\frac{NF}{2M} = \frac{5080 \times 10 \text{ kHz}}{2 \times 100} \approx 2.54 \frac{\text{Mmul}}{\text{s}}$

possibly by exploiting filter symmetry



- a) transition band extends from 45 Hz - 150 Hz (Controls filter order)
- b) Sampling rate @ o/p is 200 Hz; Nyquist is 100 Hz  
 $\Rightarrow$  aliasing of frequencies from (100 - 150) Hz to the (50 - 100 Hz) band
- Go to Filter 2 i.e., LPF<sub>2</sub> to remove "aliasing" energy

## Filter Specifications for 2-stage design

- 1) Pass band ripple for each stage is approx.  $\delta_P/2$   
(Pass band ripples add up with a 'cascade')
- 2) Stop band ripple only gets reduced

1<sup>st</sup> stage

$$N_1 \approx \frac{D_{\infty} (\delta_P/2, \delta_S)}{(150 - 45) / 10 \text{ KHz}} \approx 263$$

$$\text{Multiplications/s for stage 1} = \frac{NF}{2M_1} = \frac{263 \times 10 \text{ KHz}}{2 \times 50} = \frac{52,600}{2} \text{ Mult/s}$$

$$\begin{array}{c} \text{2nd Stage} \\ \hline N_2 = \frac{D_{\omega}(\delta_{p/2}, \delta_s)}{(50 - 45)/200} \approx 111 \end{array}$$

$$\text{Multiplications / s} = \frac{111 \times 200}{\textcircled{2} \times 2} = \frac{11000}{2} \text{ Muls/s}$$

Overall computations for the 2<sup>nd</sup> Stage design

$$\frac{1}{\textcircled{2}} (52,600 + 11,000) \text{ Muls/s}$$

Assuming filter symmetry  $\rightarrow$

Comparing to the single stage design, we have  
nearly 8:1 improvement ( SIGNIFICANT! )

### Advantages of multistage designs

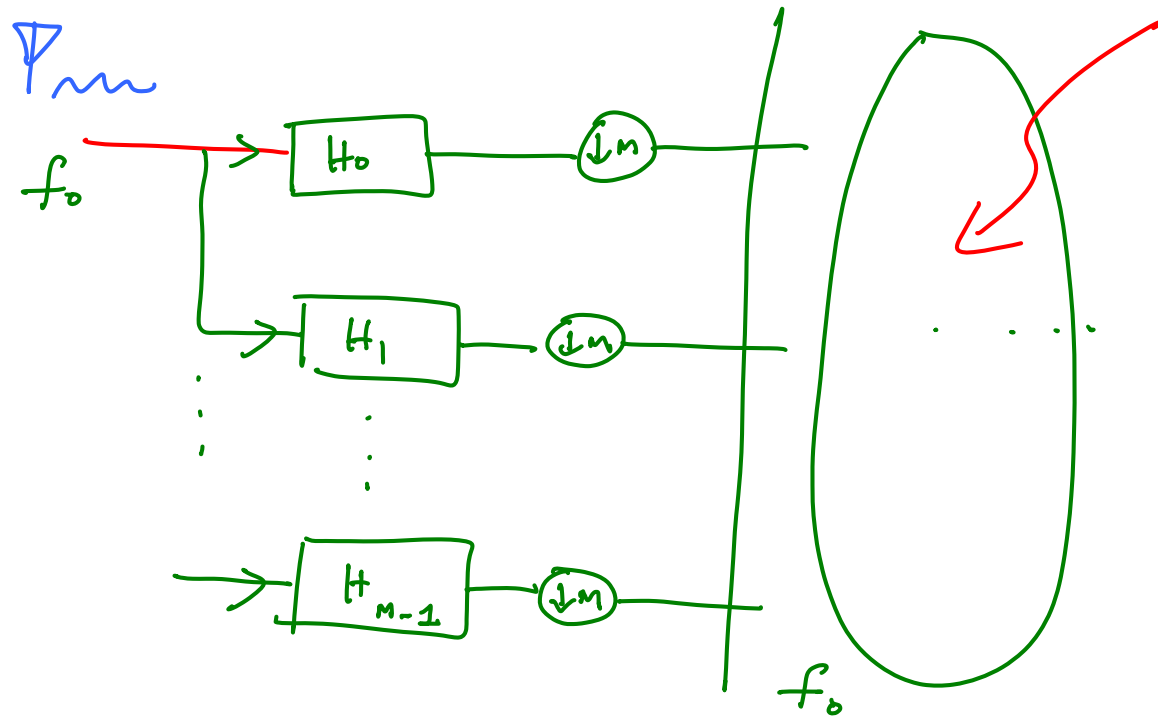
- 1) Significantly reduced computations.
- 2) Reduced storage
- 3) Simplified filter design
- 4) Reduced finite word length effects  
( lower round off noise & coeff sensitivity )

### Drawbacks

- 1) Increased control structure required to implement the design
  - 2) Do your design over all choice of  $M_i$ 's
- Ex:  $100 = 50 \times 2$   
 $100 = 10 \times 10$   
 $100 = 20 \times 5$

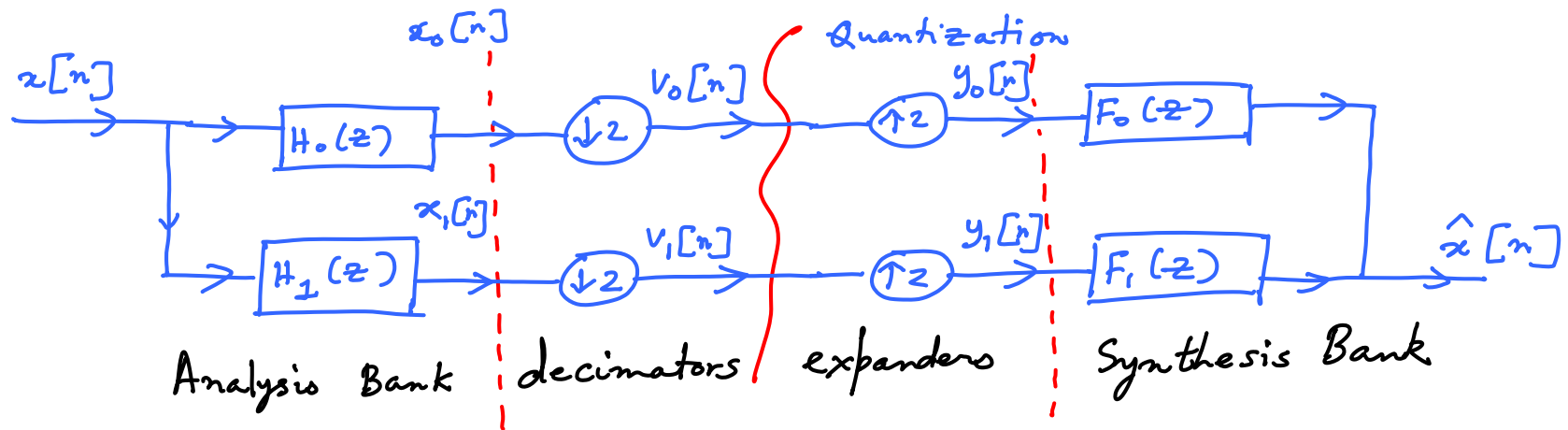
## 2 - channel Filter Bank

Filter Bank: Basically a bank of filters



Coding / Compression  
etc  
..

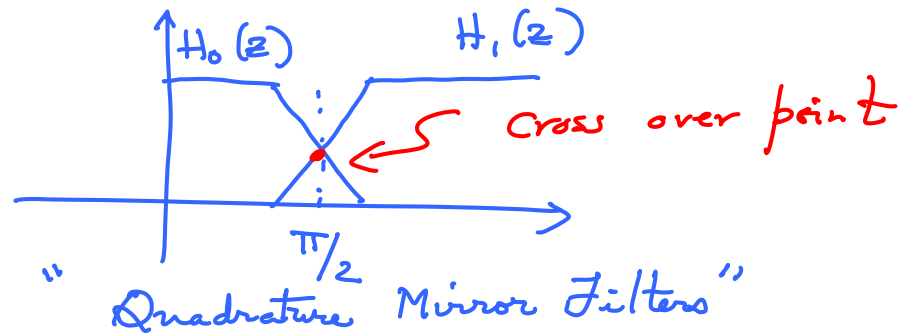




The decimated signals  $v_0[n]$  and  $v_1[n]$  are coded in such a way that the 'special properties' of the subband are exploited.

These properties include :

- a) energy level
- b) perceptive importance



The reconstructed signal  $\hat{x}[n]$  can suffer from several artifacts

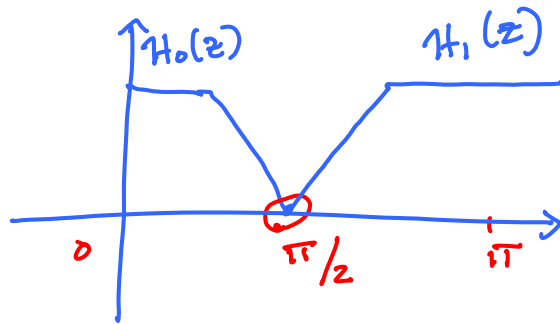
- a) Aliasing error
- b) Amplitude distortion
- c) Phase distortion

Our goal would be to design synthesis filters to overcome these limitations.

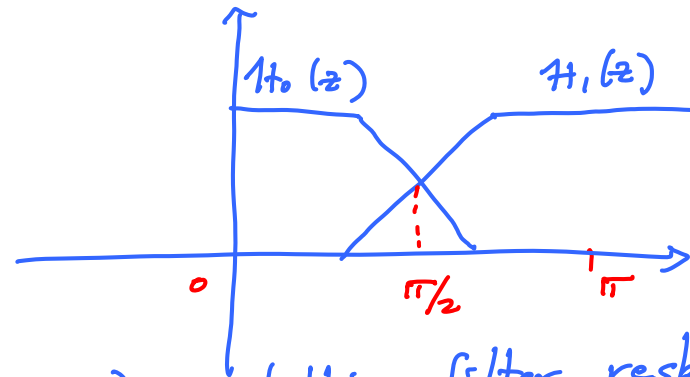
## Aliasing / Imaging

In practice, analysis filters have stop band gain

non zero transition bandwidth  $\xi$



- Stop band attenuations are sufficiently large
- Effect of aliasing is not predominant
- Severe attenuation @  $\pi/2$
- Noise amplification during synthesis.



- Overlapping filter responses  $\Rightarrow$  Possibility of aliasing
- There is gradual attenuation @  $\pi/2$   $\Rightarrow$  Noise amplification may not be all that bad during synthesis

Expression for the reconstructed signal

$$X_k(z) = H_k(z) X(z) \quad k=0, 1$$

With  $M=2$ , the o/p of the decimators are

$$V_k(z) = \frac{1}{2} \left[ X_k(z^{1/2}) + X_k(-z^{1/2}) \right]$$

'aliasing part'

post expansion,

$$\begin{aligned} Y_k(z) &= V_k(z^2) \\ &= \frac{1}{2} \left[ X_k(z) + X_k(-z) \right] \\ &= \frac{1}{2} \left[ H_k(z) X(z) + H_k(-z) X(-z) \right] \end{aligned}$$

Reconstructed signal  $\hat{X}(z)$  is

$$\hat{X}(z) = F_0(z) Y_0(z) + F_1(z) Y_1(z)$$

$$\therefore \hat{X}(z) = \frac{1}{2} \left[ H_0(z) F_0(z) + H_1(z) F_1(z) \right] X(z) + \frac{1}{2} \left[ H_0(-z) F_0(z) + H_1(-z) F_1(z) \right] X(-z)$$

$$2 \hat{X}(z) = \underbrace{\begin{bmatrix} X(z) & X(-z) \end{bmatrix}}_{\text{due to decimation}} \underbrace{\begin{bmatrix} H_0(z) & H_1(z) \\ H_0(-z) & H_1(-z) \end{bmatrix}}_{\text{Alias component matrix (AC matrix)}} \underbrace{\begin{bmatrix} F_0(z) \\ F_1(z) \end{bmatrix}}_{\text{Synthesis filters}} \underbrace{X(-z)}_{\text{Aliasing part}}$$

For alias cancellation,

$$H_0(-z) F_0(z) + H_1(-z) F_1(z) = 0$$

$$\left. \begin{aligned} F_0(z) &= H_1(-z) \\ F_1(z) &= -H_0(-z) \end{aligned} \right\}$$

Given  $\{H_0, H_1\}$ , we can obtain  $\{F_0(z), F_1(z)\}$  as above to remove 'aliasing' error  
Analysis bank

NOTE: If we adopt the QMF design, we can construct  $H_1(z) = H_0(-z)$   
With QMF, given  $H_0$ , we can construct  $H_1$  and populate all the other filters towards alias cancellation.

## Amplitude & Phase distortion

With a 2 channel filter bank, free of aliasing,

$$\hat{X}(z) = T(z) X(z) \quad \text{where}$$

$$T(z) = \frac{1}{2} \left[ H_0(z) F_0(z) + H_1(z) F_1(z) \right]$$

distortion transfer function

$$T(z) = \frac{1}{2} \left[ H_0(z) H_1(-z) - H_1(z) H_0(-z) \right]$$
$$T(z) \Big|_{z=e^{j\omega}} = |T(e^{j\omega})| e^{j\phi(\omega)}$$

Unless

$$|T(e^{j\omega})| = d \neq 0 \quad \forall \omega,$$

we have magnitude distortion

Unless

$$\phi(\omega) = a + b\omega$$

$\hat{X}(e^{j\omega})$  suffers from phase distortion.

$$\text{Let } \begin{aligned} V(z) &= H_0(z) H_1(-z) \\ V(-z) &= H_0(z) H_1(z) \end{aligned}$$

$$T(z) = \frac{1}{2} [V(z) - V(-z)]$$

$\Rightarrow T(z)$  has only odd powers of  $z$

$$T(z) = z^{-1} S(z^2)$$

$|T(z)|$  has a period of  $\pi$  instead of  $2\pi$ !



## Perfect Reconstruction Filter Bank

For the PR,  $T(z) = c z^{-n_0}$

$$\Rightarrow \hat{x}(n) = c x(n-n_0)$$

Consider the QMF bank system,

Suppose  $H_1(z) = H_0(-z) \Rightarrow H_1(z)$  is a good HPF  
if  $H_0(z)$  is a good LPF!

$$|H_1(e^{j\omega})| = |H_0(e^{j(\pi-\omega)})|$$

$$\begin{aligned}
 T(z) &= \frac{1}{2} \left[ H_0^2(z) - H_1^2(z) \right] \\
 &= \frac{1}{2} \left[ H_0^2(z) - H_0^2(-z) \right]
 \end{aligned}$$

For phase distortion :

$$\text{Let } H_0(z) = \sum_{n=0}^N h_0(n) z^{-n} \quad h_0(n) \text{ is real}$$

$$\text{Let } h_0(n) = \pm h_0(N-n) \quad (\text{linear phase})$$

$$\text{But for LPF, } h_0(n) = h_0(N-n)$$

$$H_0(e^{j\omega}) = e^{-j\omega L(\omega)} R(\omega)$$

Exercise!

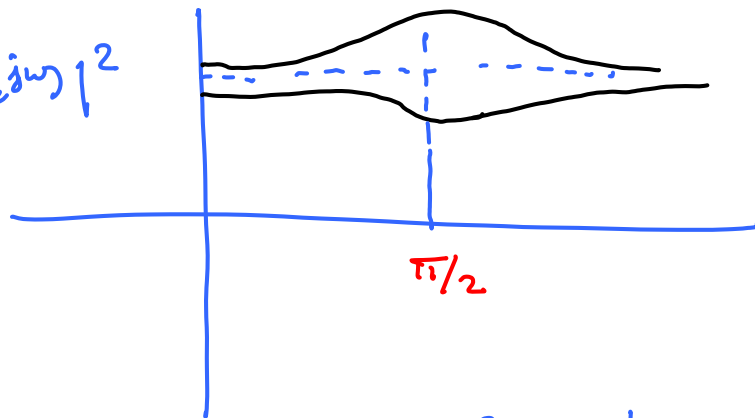
$$\rightarrow T(e^{j\omega}) = \frac{1}{2} e^{-j\omega N} \left( |H_0(e^{j\omega})|^2 - (-1)^N |H_0(e^{j(\pi-\omega)})|^2 \right)$$

If  $N$  is even,  $T(e^{j\omega})$  reduces to zero @  $\omega = \pi/2$   
leading to 'severe attenuation'

## Minimizing residual amplitude distortion

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$$|H_0(e^{j\omega})|^2 + |H_1(e^{j\omega})|^2$$



GOAL:

$$|H_0(e^{j\omega})|^2 + |H_1(e^{j\omega})|^2 = 1 \quad (\text{approximately})$$

Let us formulate an objective function

$$\phi = \alpha \phi_1 + (1-\alpha) \phi_2 \quad \text{with } 0 < \alpha < 1$$

$$\phi_1 = \int_{\omega_s}^{\pi} |H_0(e^{j\omega})|^2 d\omega$$

$$\phi_2 = \int_{\omega_s}^{\pi} \left( 1 - |H_0(e^{j\omega})|^2 - |H_0(e^{j(\pi-\omega)})|^2 \right)^2 d\omega$$

$$h_0[n] = \underset{h_0[n]}{\text{min}} \phi \quad (\text{Johnston 1980})$$

