Homework #5 solution key

Prayag Neural networks and learning systems-I

April 23, 2019

Problem 8.5.

Solution. For the matched filter considered in Example 2, it is given that the random vector $\mathbf{X} = \mathbf{s} + \mathbf{V}$, where the signal component is represented by \mathbf{s} has a fixed Euclidean norm of one, i.e., $\sqrt{\mathbf{s}^{\mathrm{T}}\mathbf{s}} = 1 \implies \mathbf{s}^{\mathrm{T}}\mathbf{s} = 1$. The random vector \mathbf{V} , represents the additive noise component and has zero mean and covariance matrix $\sigma^{2}\mathbf{I}$. The correlation matrix of \mathbf{X} is given by $\mathbf{R} = \mathbf{s}\mathbf{s}^{\mathrm{T}} + \sigma^{2}\mathbf{I}$. The largest eigenvalue of the correlation matrix \mathbf{R} and the corresponding eigenvector are $\lambda_{1} = 1 + \sigma^{2}$ and $\mathbf{q}_{1} = \mathbf{s}$ respectively. Let us post multiply the correlation matrix by the eigenvector \mathbf{q}_{1} .

$$\mathbf{R}\mathbf{q}_{1} = (\mathbf{s}\mathbf{s}^{\mathrm{T}} + \sigma^{2}\mathbf{I}) \mathbf{q}_{1}$$

= $(\mathbf{s}\mathbf{s}^{\mathrm{T}} + \sigma^{2}\mathbf{I}) \mathbf{s}$
= $\mathbf{s}\mathbf{s}^{\mathrm{T}}\mathbf{s} + \sigma^{2}\mathbf{s}$
= $\mathbf{s} + \sigma^{2}\mathbf{s}$ (since $\mathbf{s}^{\mathrm{T}}\mathbf{s} = 1$)
= $(1 + \sigma^{2}) \mathbf{s}$
= $\lambda_{1}\mathbf{s}$
= $\lambda_{1}\mathbf{q}_{1}$

Therefore the given parameters satisfy the basic relation of $\mathbf{R}\mathbf{q}_1 = \lambda_1\mathbf{q}_1$.

Problem 8.15.

Solution. Let the total number of inputs be N. The data \mathbf{x}_i is projected using a kernel to get the projected data set $\phi(\mathbf{x}_i)$. Let $\tilde{\phi}(\mathbf{x}_i)$ be the projected data points after centralizing the data as given below

$$\tilde{\phi}(\mathbf{x}_i) = \phi(\mathbf{x}_i) - \frac{1}{N} \sum_{l=1}^N \phi(\mathbf{x}_l).$$

We can get the corresponding elements of the gram matrix \tilde{K} as below:

$$\begin{split} \tilde{k}_{ij} &= \tilde{\phi}^{\mathrm{T}}(\mathbf{x}_{i})\tilde{\phi}(\mathbf{x}_{j}) \\ &= \left(\phi(\mathbf{x}_{i}) - \frac{1}{N}\sum_{m=1}^{N}\phi(\mathbf{x}_{m})\right)^{\mathrm{T}}\left(\phi(\mathbf{x}_{j}) - \frac{1}{N}\sum_{n=1}^{N}\phi(\mathbf{x}_{n})\right) \\ &= \phi(\mathbf{x}_{i})^{\mathrm{T}}\phi(\mathbf{x}_{j}) - \frac{1}{N}\sum_{m=1}^{N}\phi^{\mathrm{T}}(\mathbf{x}_{m})\phi(\mathbf{x}_{j}) - \frac{1}{N}\sum_{n=1}^{N}\phi^{\mathrm{T}}(\mathbf{x}_{i})\phi(\mathbf{x}_{n}) + -\frac{1}{N^{2}}\sum_{m=1}^{N}\sum_{n=1}^{N}\phi^{\mathrm{T}}(\mathbf{x}_{m})\phi(\mathbf{x}_{n}) \\ &= k_{ij} - \frac{1}{N}\sum_{m=1}^{N}k_{mj} - \frac{1}{N}\sum_{n=1}^{N}k_{in} + -\frac{1}{N^{2}}\sum_{m=1}^{N}\sum_{n=1}^{N}k_{mn} \end{split}$$

A compact representation of the above in the matrix form is given by

$\tilde{\mathbf{K}} = \mathbf{K} - \mathbf{N}\mathbf{K} - \mathbf{K}\mathbf{N} + \mathbf{N}\mathbf{K}\mathbf{N}$

where **N** is an $N \times N$ matrix with all entries as $\frac{1}{N}$.

Problem 8.16.

Solution. It is given that the eigenvector \tilde{q} of the correlation matrix $\tilde{\mathbf{R}}$ is normalized to unit length, that is,

$$\tilde{q}_k^{\Gamma} \tilde{q}_k = 1 \text{ for } k = 1, 2, \dots, l$$
 (1)

where it is assumed that the eigenvalues of \mathbf{K} are arranged in descending order with λ_l being the smallest nonzero eigenvalue of the Gram matrix \mathbf{K} . We know that

$$\tilde{q} = \sum_{j=1}^{N} \alpha_j \phi(x_j) \tag{2}$$

$$K\alpha = \lambda\alpha \tag{3}$$

Using (2) in (1) and upon simplifying, we get

$$1 = \tilde{q}_{k}^{\mathrm{T}} \tilde{q}_{k}$$

$$= \sum_{i=1}^{N} \sum_{j=1}^{N} \alpha_{ki}^{\mathrm{T}} \alpha_{kj} \phi(x_{i})^{\mathrm{T}} \phi(x_{j})$$

$$= \alpha_{k}^{\mathrm{T}} K \alpha_{k}$$

$$= \alpha_{k}^{\mathrm{T}} \lambda_{k} \alpha_{k} \quad (\text{Using } (3))$$

$$= \lambda_{k} \alpha_{k}^{\mathrm{T}} \alpha_{k}$$

$$\frac{1}{\lambda_{k}} = \alpha_{k}^{\mathrm{T}} \alpha_{k} \quad \text{for } k = 1, 2, \dots, l.$$

Therefore, we see that normalization of the eigenvector α of the Gram matrix **K** is equivalent to the requirement of Eq(8.109) to be satisfied.