

Indian Institute of Science  
E9–252: Mathematical Methods and Techniques in Signal Processing  
Instructor: Shayan G. Srinivasa  
Homework #6 Solutions, Fall 2017

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Late submission policy: Points scored = Correct points scored  $\times e^{-d}$ ,  $d = \#$  days late  
**Assigned date:** Oct. 9<sup>th</sup> 2017      **Due date:** Oct. 23<sup>rd</sup> 2017 by end of the day

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**PROBLEM 1:**

Problem 3.19 from P.P Vaidyanathan's Book

(9 points)

**Solution:** From the figure in the question, we obtain

$$G_m(z) = \frac{k_m^* + z^{-1}G_{m-1}(z)}{1 + k_m z^{-1}G_{m-1}(z)}$$

The poles of  $G_m(z)$  are the zeros of  $1 + k_m z^{-1}G_{m-1}(z)$ . Thus,

$$\begin{aligned} 1 + k_m z^{-1}G_{m-1}(z) = 0 &\implies z^{-1} = -\frac{1}{k_m G_{m-1}(z)} \\ z = -k_m G_{m-1}(z) &\implies |z| = |k_m| |G_{m-1}(z)| = |k_m| < 1 \end{aligned}$$

Note that  $z$  is a variable in the above case. Thus, the poles of  $G_m(z)$  are inside unit circle. As  $|G_{m-1}(z)| = 1 \implies G_{m-1}(z) = e^{jf(z)}$ .

$$|G_m(z)| = \left| \frac{k_m^* + z^{-1}G_{m-1}(z)}{1 + k_m z^{-1}G_{m-1}(z)} \right| = \frac{|k_m^* + z^{-1}G_{m-1}(z)|}{|1 + k_m z^{-1}G_{m-1}(z)|}$$

If  $k_m = a + jb$ ,

$$\begin{aligned} |k_m^* + z^{-1}G_{m-1}(z)| &= |a - jb + \cos(f(z) - 1) + j\sin(f(z) - 1)| \\ &= (a^2 + \cos^2(f(z) - 1) + 2a\cos(f(z) - 1) + b^2 + \sin^2(f(z) - 1) - 2b\sin(f(z) - 1))^{1/2} \\ |1 + k_m z^{-1}G_{m-1}(z)| &= |1 + (a + jb)(\cos(f(z) - 1) + j\sin(f(z) - 1))| \\ &= (1 + a^2\cos^2(f(z) - 1) + b^2\sin^2(f(z) - 1) - 2b\sin(f(z) - 1) + 2a\cos(f(z) - 1) \\ &\quad - 2abc\cos(f(z) - 1)\sin(f(z) - 1) + b^2\cos^2(f(z) - 1) + a^2\sin^2(f(z) - 1) \\ &\quad + 2abc\cos(f(z) - 1)\sin(f(z) - 1))^{1/2} \\ &= (1 + a^2 + b^2 - 2b\sin(f(z) - 1) + 2a\cos(f(z) - 1))^{1/2} \\ &= |k_m^* + z^{-1}G_{m-1}(z)| \implies |G_m(z)| = 1 \end{aligned}$$

Part b) follows from induction using part a).

**PROBLEM 2:**

Problem 3.20 from P.P Vaidyanathan's Book

(10 points)

**Solution:** As  $P_0(z)$  is hermitian,  $\tilde{P}_0(z) = z^N P_0(z)$ . As  $P_1(z)$  is generalized hermitian,  $\tilde{P}_1(z) = cz^N P_1(z)$ , where  $|c| = 1$ . We prove the result by expressing  $A_0(z)$ ,  $A_1(z)$  and  $d$  in terms of  $c$ ,  $P_0(z)$ ,  $P_1(z)$  and  $D(z)$ .

$$\begin{aligned} H_0(z) &= \frac{\beta A_0(z) + \beta^* A_1(z)}{2} \implies P_0(z) = \frac{\beta A_0(z) + \beta^* A_1(z)}{2} D(z) \\ H_1(z) &= d \frac{\beta A_0(z) - \beta^* A_1(z)}{2} \implies P_1(z) = d \frac{\beta A_0(z) - \beta^* A_1(z)}{2} D(z) \\ \implies A_0(z) &= \left( \frac{P_0(z)}{D(z)} + \frac{P_1(z)}{dD(z)} \right) \frac{1}{\beta} \text{ and } A_1(z) = \left( \frac{P_0(z)}{D(z)} - \frac{P_1(z)}{dD(z)} \right) \frac{1}{\beta^*} \end{aligned}$$

$$|H_0(z)|^2 + |H_1(z)|^2 = 1 \implies |P_0(z)|^2 + |P_1(z)|^2 = |D(z)|^2 \implies z^N P_0^2(z) + cz^N P_1^2(z) = |D(z)|^2.$$

$$\begin{aligned} |A_0^2(z)| &= \frac{1}{|D(z)|^2} \frac{z^N}{\beta\beta^*} \left( P_0(z) + \frac{P_1(z)}{d} \right) \left( P_0(z) + c \frac{P_1(z)}{d^*} \right) \\ &= \frac{z^N}{|D(z)|^2} \left( P_0^2(z) + \frac{cP_0(z)P_1(z)}{d^*} + cP_1^2(z) + \frac{P_0(z)P_1(z)}{d} \right) \\ &= \frac{1}{|D(z)|^2} \left( |D(z)|^2 + \left( \frac{c}{d^*} + \frac{1}{d} \right) P_0(z)P_1(z) \right) \\ &= 1 + \left( \frac{c}{d^*} + \frac{1}{d} \right) \frac{P_0(z)P_1(z)}{|D(z)|^2}. \\ |A_1^2(z)| &= \frac{1}{|D(z)|^2} \frac{z^N}{\beta\beta^*} \left( P_0(z) - \frac{P_1(z)}{d} \right) \left( P_0(z) - c \frac{P_1(z)}{d^*} \right) \\ &= \frac{z^N}{|D(z)|^2} \left( P_0^2(z) - \frac{cP_0(z)P_1(z)}{d^*} + cP_1^2(z) - \frac{P_0(z)P_1(z)}{d} \right) \\ &= 1 - \left( \frac{c}{d^*} + \frac{1}{d} \right) \frac{P_0(z)P_1(z)}{|D(z)|^2}. \end{aligned}$$

Let us choose  $d : \left( \frac{c}{d^*} + \frac{1}{d} \right) = 0$ , then,  $|A_0^2(z)| = |A_1^2(z)| = 1$ . We can choose such  $d$  as  $\frac{c}{d^*} = \frac{1}{d} \implies |c| = 1$ . Thus, we can obtain  $A_0(z)$  and  $A_1(z)$  as unit magnitude all pass filters with  $|\beta| = |d| = 1$ .

**PROBLEM 3:**

Problem 3.21 from P.P Vaidyanathan's Book

(6 points)

**Solution:** If  $A_1(z) = cA_0(z)$ , then  $G(z) = (1+c)A_0(z) \implies |G(z)| = |1+c||A_0(z)| = |1+c|b$  where  $|A_0(z)| = b$ . Thus,  $G(z)$  is all pass filter. If  $G(z) = A_0(z) + A_1(z)$  is all pass filter, then, as  $A_0(z)$  and  $A_1(z)$  are all pass filters they can be represented by,

$$A_0(z) = be^{jf(z)} \text{ and } A_1(z) = ce^{jh(z)}$$

$G(z)$  is obtained as:

$$\begin{aligned} G(z) &= A_0(z) + A_1(z) = be^{jf(z)} + ce^{jh(z)} \\ &= b\cos f(z) + jbs\sin f(z) + c\cosh(z) + jc\sinh(z) \\ |G(z)|^2 &= b^2\cos^2 f(z) + c^2\cos^2 h(z) + 2bcc\cos f(z)\cosh(z) + b^2\sin^2 f(z) + c^2\sin^2 h(z) + 2bc\sin f(z)\sinh(z) \\ &= b^2 + c^2 + 2bcc\cos(f(z) - h(z)) \end{aligned}$$

As  $b$ ,  $c$  and  $|G(z)|^2$  are constant, thus,

$$\begin{aligned} \cos(f(z) - h(z)) &= d \text{ (const)} \implies f(z) - h(z) = \cos^{-1}d = d' \implies h(z) = f(z) - d' \\ \implies A_1(z) &= ce^{jh(z)} = ce^{jf(z)-d'} = mA_0(z). \end{aligned}$$